

# CogSci 109: Lecture 8

Tuesday Oct 17, 2006

Color examples and basic fits

# Announcements

- Hw 2 extended to Thurs Oct 19
- Hints page
- Reading for least squares and other fits
- Chancellor's challenge

# Aside: You don't have to know everything to understand things

- Your equations and math concepts are ways of expressing the underlying reality
- But the reality is expressed THROUGH that
- The true reality is its own thing, but the graphs, models, equations and so on become expressions of the underlying truth, yielding potential insights
- Do not judge yourself or compare, do not tell yourself you are 'not a math/computer person,' inferior to another, nor should you feel superior
  - Address the reality of the moment
  - If you don't know something, read about it, think, ponder, experience, but do not judge

# Update: the big picture

- Where we are
- Where we're going

# Homework hints

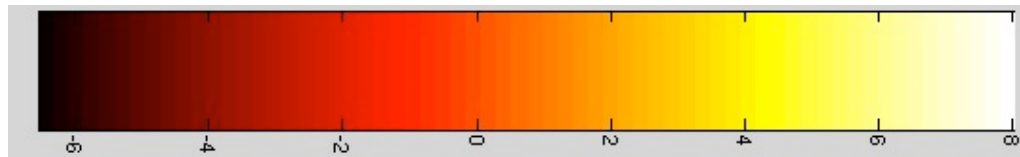
- Reminder - Hertz
  - abbreviated Hz = cycles/second
- The hints page - check for your answer there
- Problems with crashing?
  - At the command prompt type  
opengl neverselect

# More motivation for math and programming

- Why so much math? How does that relate to programming again?
  - Math provides a

# Some specific matlab color map examples

- What if I want to examine the boundaries of my data?
  - I only want to see the extremes
  - We can create a custom color map!



# Creating the color map (r,g,b) components

- To create a custom color map we need to make a matrix which is Dim nx3, range [0,1]
- Each column is the range of either red, green, blue
- We could write it by hand:

$$M = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

- Type it into a matlab variable:

```
M = [1 0 0; 0 0 0; 0 0 0; 0 0 0; 0 1 0];
```



# Now what?

- We create our plot, let's create some data:

```
X = peaks(50);
```

- And plot it using *pcolor*:

```
pcolor(X)
```

```
colormap(M)
```

# Here's what we get...

- As you can see this can be very useful for feature detection
- But let's say we want to make a smooth map, how do we do that?



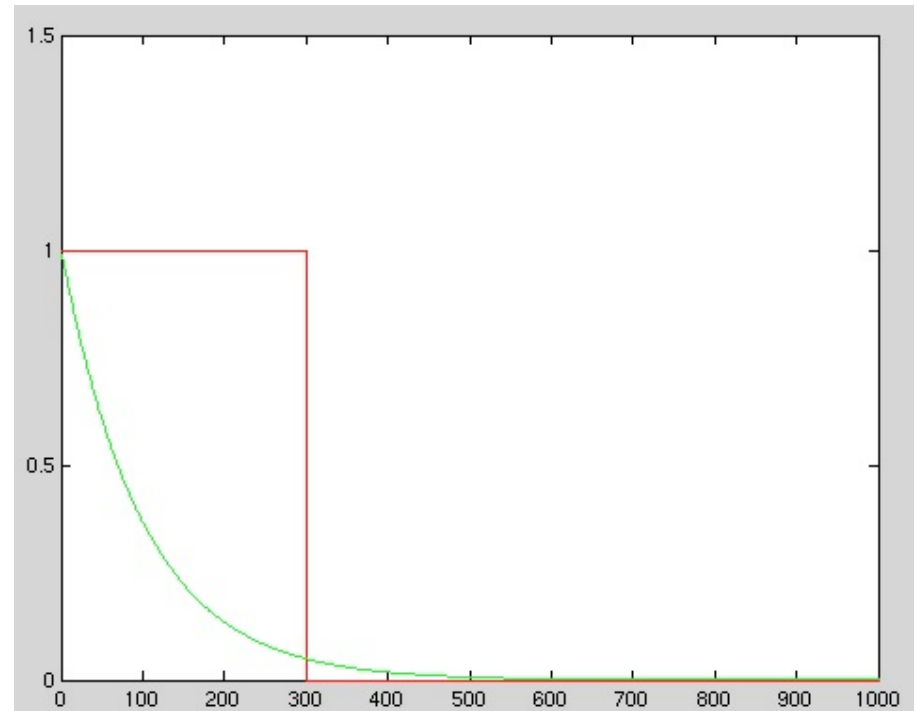
# Creating smooth color map functions

- Instead of typing the matrix in manually, let's construct the functions we need to make transitions smooth from one color to the next
- Create many values in between 0 and 1
- Two things of note
  - The length of your colormap array is up to you, the more numbers and the smaller the transitions, the more smooth the colors look (crayons vs. airbrushing)
  - The colors are mapped so the  
`range(0,1) -> range( min(data), max(data) )`

# Looking at smooth transitions

- Comparison after matching the number of values in the simple color variation (1 -> 0) vs. a smooth function from 1->0
- Uses the equation...
  - (for Decreasing:)

$$r = \exp(-x)$$
$$x = 0 : .01 : 100$$



# The final smooth color map

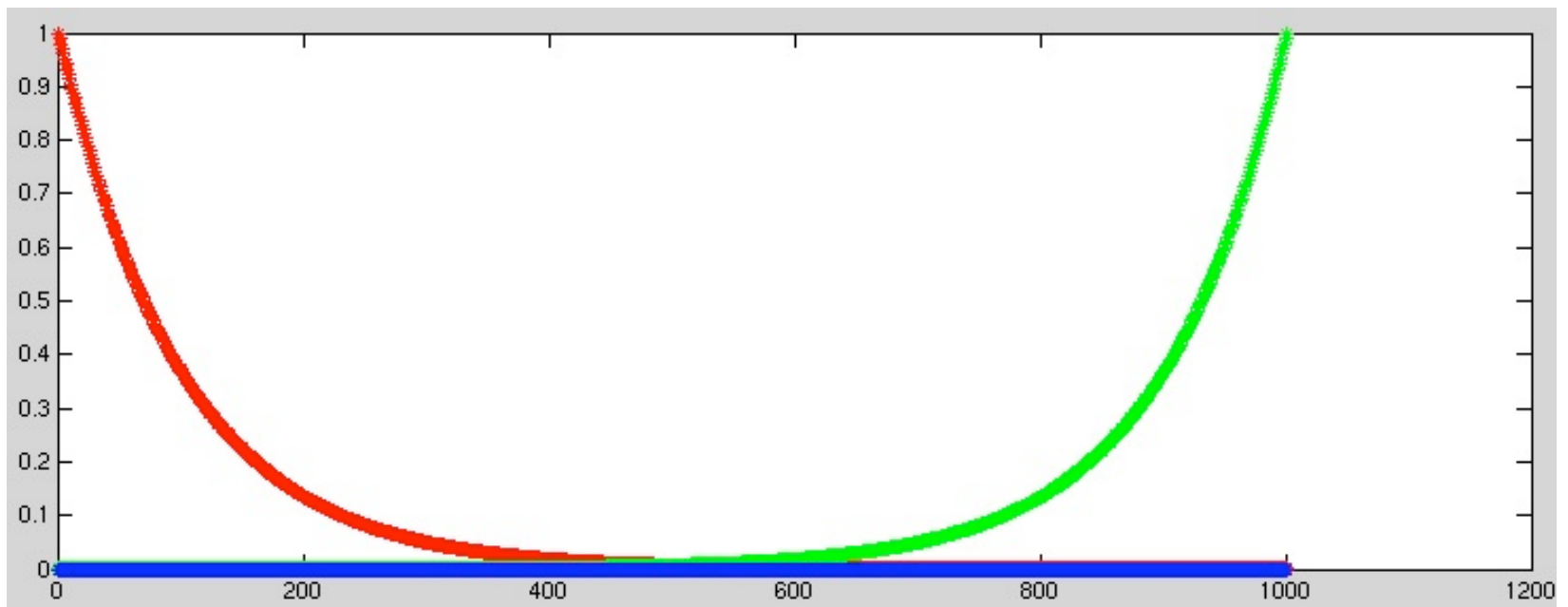
- And equations:

– Decreasing:

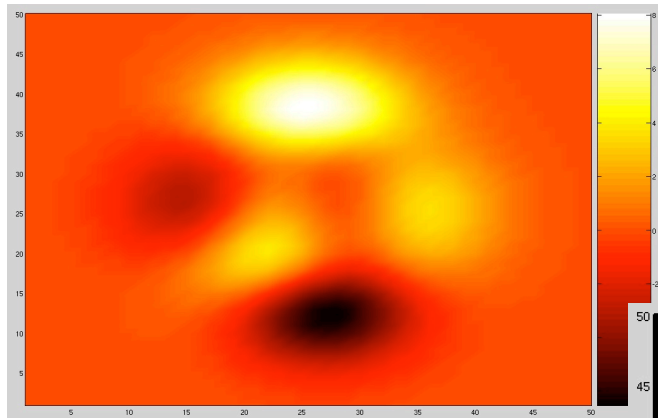
$$r = \exp(-x)$$
$$x = 0 : .01 : 10$$

–Increasing:

$$g = \frac{\exp(x)}{\max[\exp(x)]}$$
$$x = 0 : .01 : 10$$

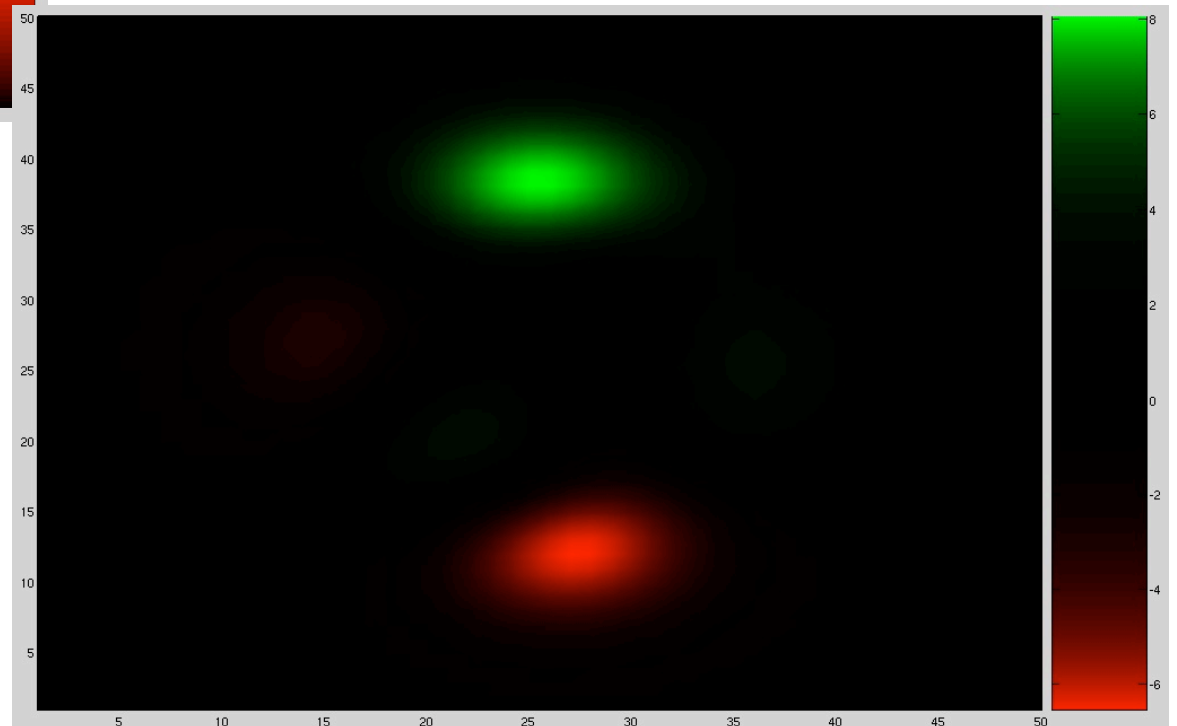


# Results of our custom color map



<- Using the built-in 'hot' color map

Using our color map->



# Matlab implementation...

- To matlab...

# Covariance clarifications



# Linear least squares

- You're probably all familiar with linear regression -- fitting a line to a bunch of data.
- more formally fitting  $y = mx + b$  for paired  $x, y$  data (can also do multidimensional)
- Let's see how it's done mathematically

# Let's start by considering an easier question...

- We have 2 points, and want to fit a line to them
- $(1,2)$  ,  $(3,4)$
- How would you solve this problem?
- We want  $y=mx+b$  (we need **m** and **b**)
  - Substitute each point in

$$\begin{array}{l} 2 = m(1) + b \\ 4 = m(3) + b \end{array}$$

# Example continued

- And solve for **b** first, then **m**

$$b = 2 - m$$

$$4 = 3m + 2 - m$$

$$4 = 2m + 2$$

$$m = 1$$

$$b = 2 - m$$

$$b = 1$$

# Example continued

- We have two equations and two unknowns ( $m$ ,  $b$ )
- This can be written compactly as

$$\begin{bmatrix} 1 & 1 \\ 3 & 1 \end{bmatrix} \begin{Bmatrix} m \\ b \end{Bmatrix} = \begin{Bmatrix} 2 \\ 4 \end{Bmatrix}$$

- Which is of the basic form

$$Ax = b$$

- We want to find

$$x = A^{-1}b$$

# Solving $Ax=b$

- Solving for  $x = A^{-1}b$  involves computing the inverse of the A matrix
  - Insiwhatsitz? Don't worry...inverses are a way to make life easier
- There are several methods, and you can solve for arbitrarily sized problems (ie what if we want to find 100 variables? Not fun by hand:( Let's use a computer to do it for us!!!:))
  - Gaussian elimination (what you learned in linear algebra class)
    - Don't worry you won't have to do it by hand in this class!
  - Thomas algorithm, etc (and other more efficient methods computationally)
  - Matlab has gaussian elimination built-in nicely of course

# We need to remind ourselves of matrix inversion

- What is an inverse of a matrix?
- Rotation example
  - If a vector is rotated by multiplying it by a rotation matrix, then multiplying the rotated vector by the inverse rotates the vector back to its original orientation
  - Side note - a matrix times its inverse yields the identity matrix

- You can test for a matrix being the inverse of another matrix by multiplying the two, and see how close do you get to the identity matrix?

$$\boxed{AA^{-1} = I} \quad \boxed{A^{-1}A = I} \quad \boxed{AI = A} \quad \boxed{IA = A}$$

- Look up more of the definition details...see references on site
  - Homework problem, one matrix plot is an example...which could it be? Hmm...what special matrices have we just mentioned? Hmmm...how could I IDENTIFY this matrix? Hmmm...
- Dating example

# How to solve $Ax=b$ in matlab

- In matlab this can be solved for with the  $\backslash$  operator
- $A\backslash B$  is the matrix division of A into B
  - roughly the same as  $INV(A)*B$
  - computed in a different way.
    - If A is an N-by-N matrix and B is a column vector with N components, or a matrix with several such columns, then  $X = A\backslash B$  is the solution to the equation  $A*X = B$  computed by Gaussian elimination.
- Doing it in matlab:

```
mb= [1 1; 3 1]\[2;4];    %(left matrix divide)
```

# Derivation of linear least squares

- <on board>



# Another example in matlab

- consider (1,2) (3,4) (2, 3.5)

```
x=[ 1 3 2 ]
```

```
y=[ 2 4 3.5 ]
```

```
plot(x,y, '* ' )
```

- $1m + b = 2$
- $3m + b = 4$
  
- $2m + b = 3.5$

# Example continued

$$A = \begin{bmatrix} 1 & 1 \\ 3 & 1 \\ 2 & 1 \end{bmatrix}$$

$$y = \begin{bmatrix} 2 \\ 4 \\ 3.5 \end{bmatrix}$$

- if we use the  $m=1, b=1$  solution to the first two it doesn't fit the third
- e.g. 3 equations and 2 unknowns
- This is what is known as an overconstrained problem. People commonly like to find the solution that minimizes the mean square error

# Example continued

- This means we want to find the solution that minimizes

$$\sum_{\{(x,y) \text{ pairs}\}} (y-mx-b)^2$$

- Matlab again solves this with

```
mb=A\y
```

```
hold on
```

```
newA=[0 1; 5 1]
```

```
plot([0 5],newA*mb)
```

# Correlation

# Correlation as a measure of fit

- Closer to 0 worse fit
- Closer to 1 better fit

# But what if the data isn't linear?

- Nonlinear least squares
  - Polynomial fit
  - Exponential fit